

Fig.1

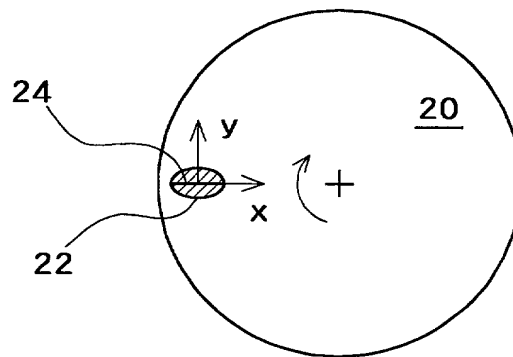


Fig.2

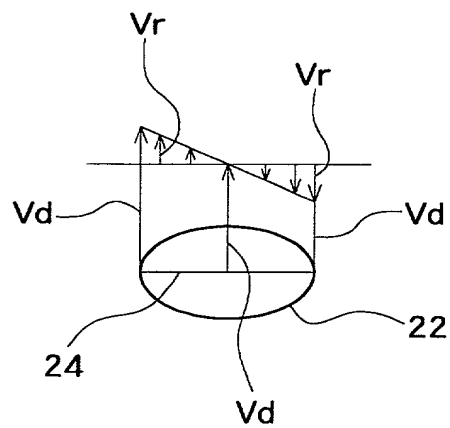


Fig.3

20067903.000001

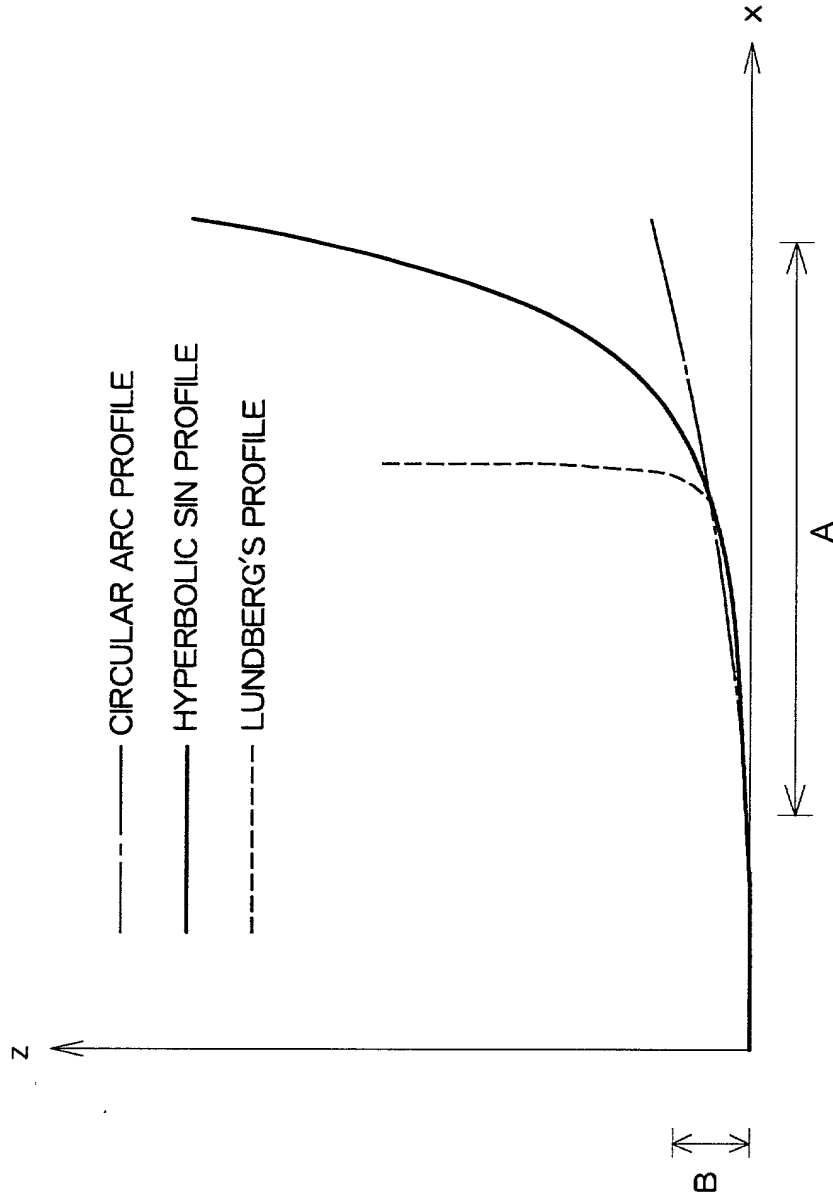


Fig.4

50000" E05/5000"

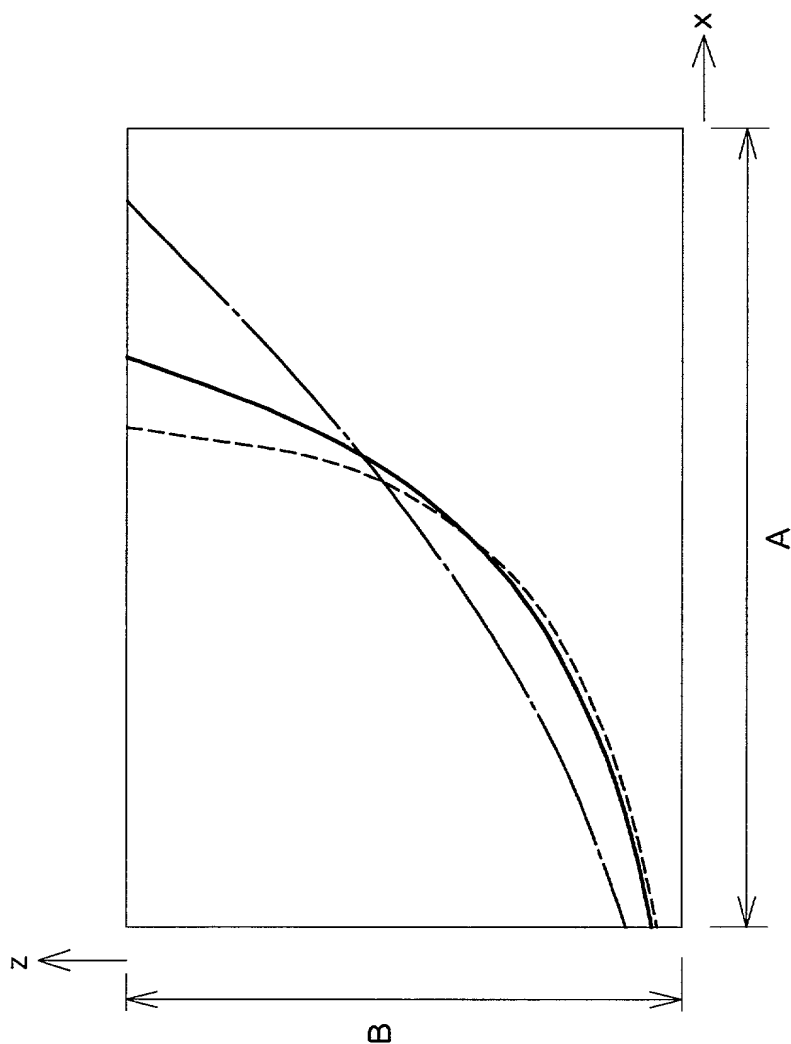


Fig.5

20250303 095629007

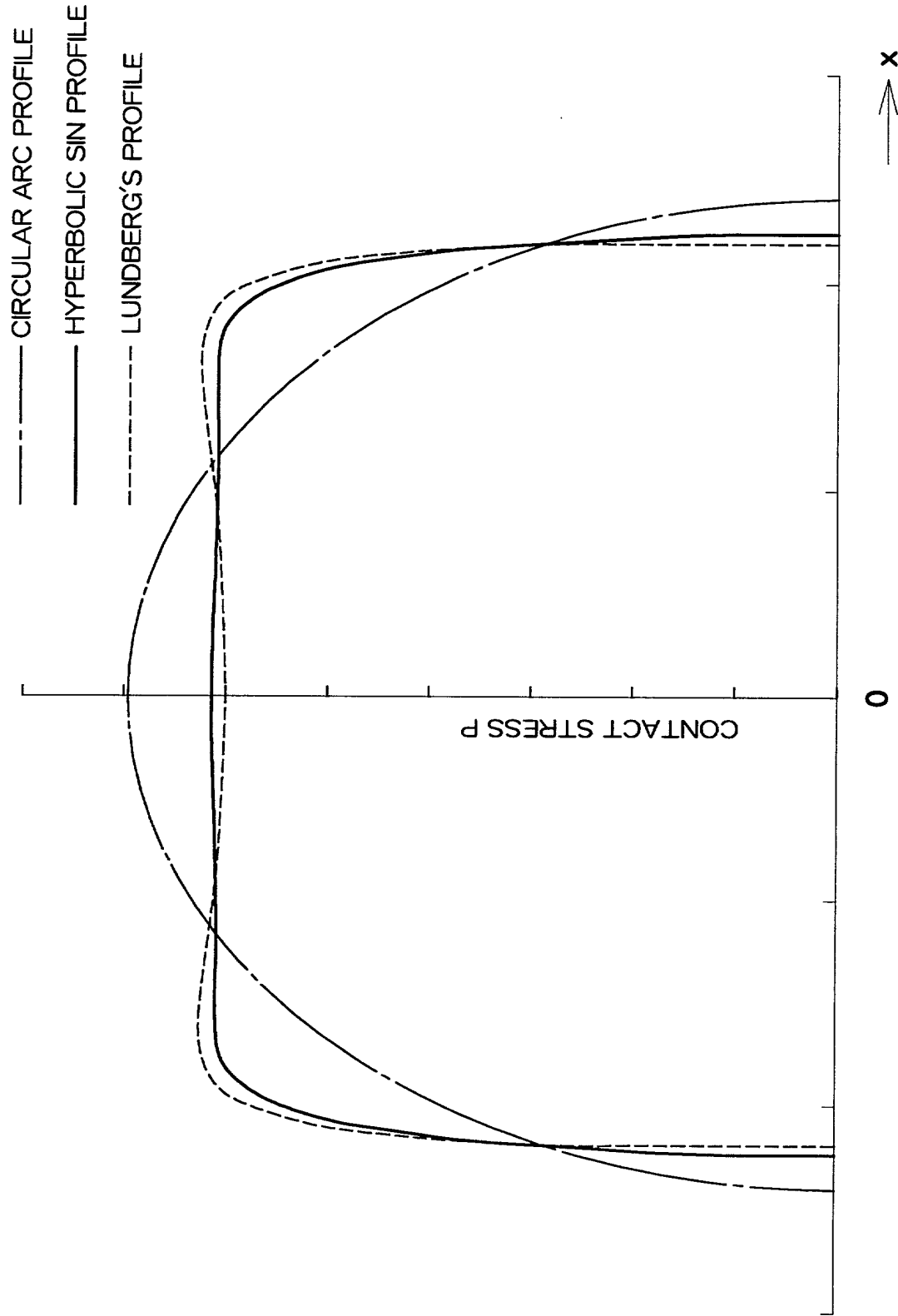
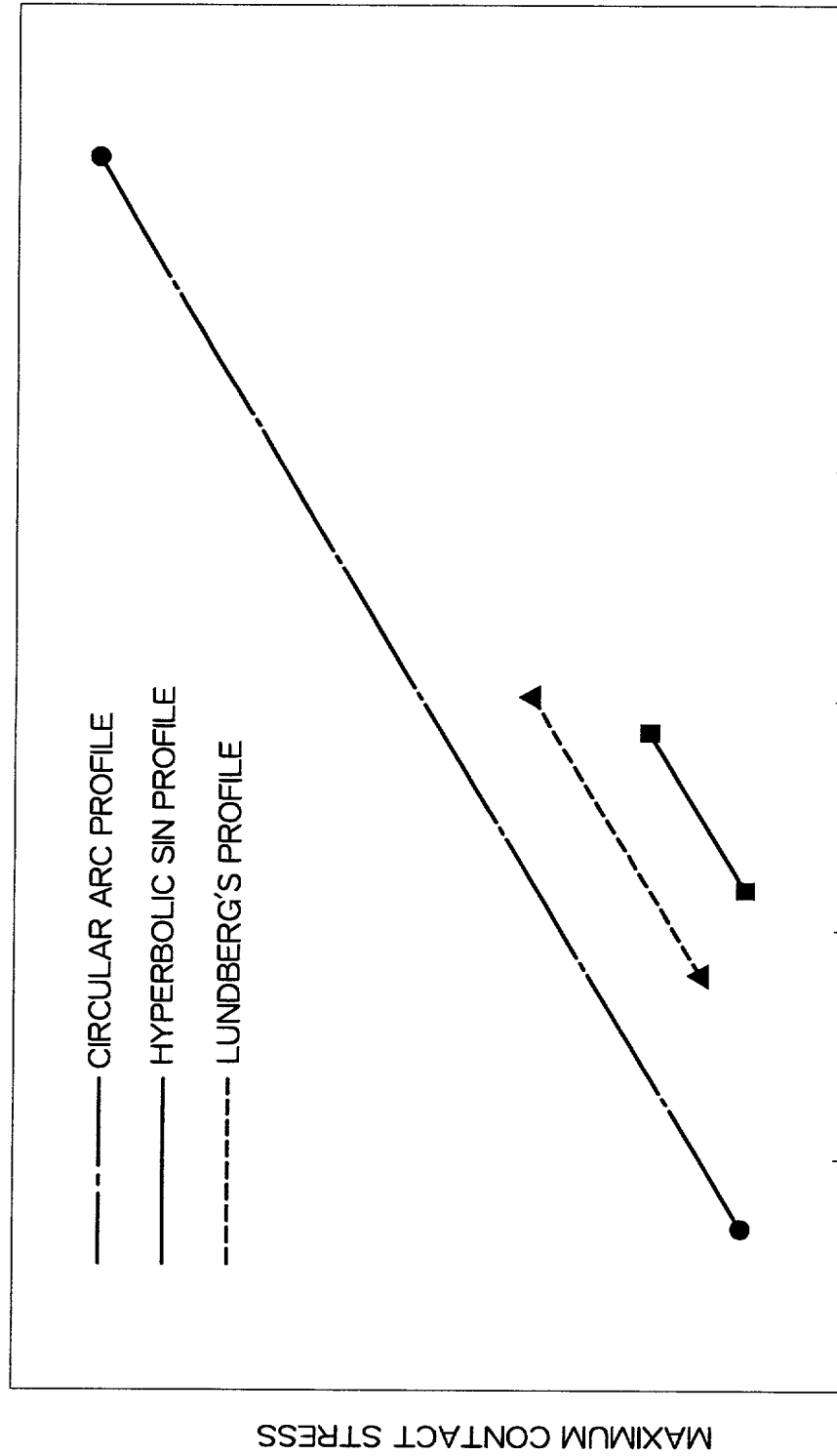


Fig.6



TRACTION COEFFICIENT

Fig.7

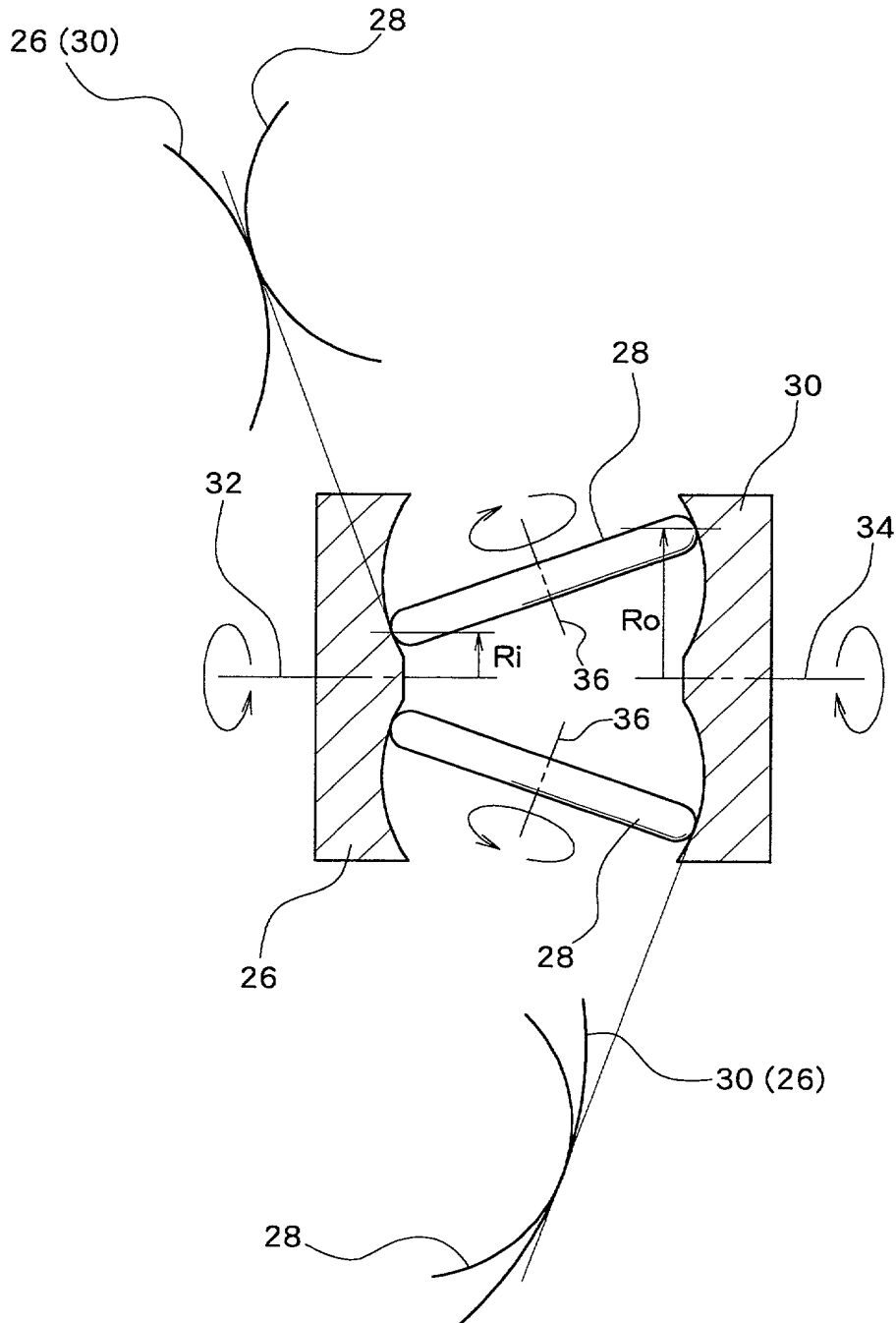


Fig.8

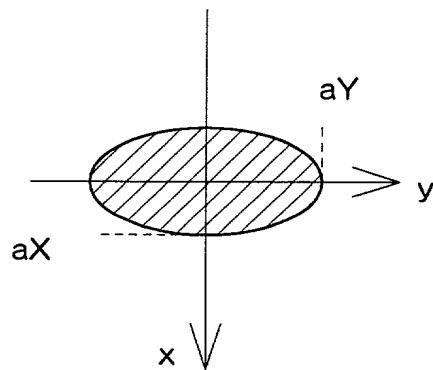


Fig.9

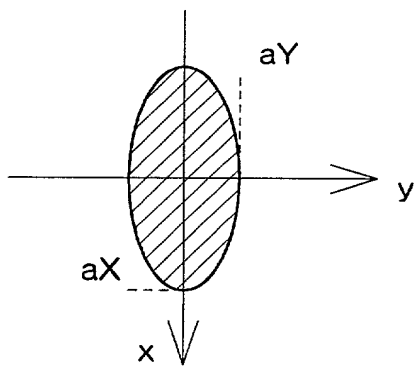


Fig.10

10067903, 050300

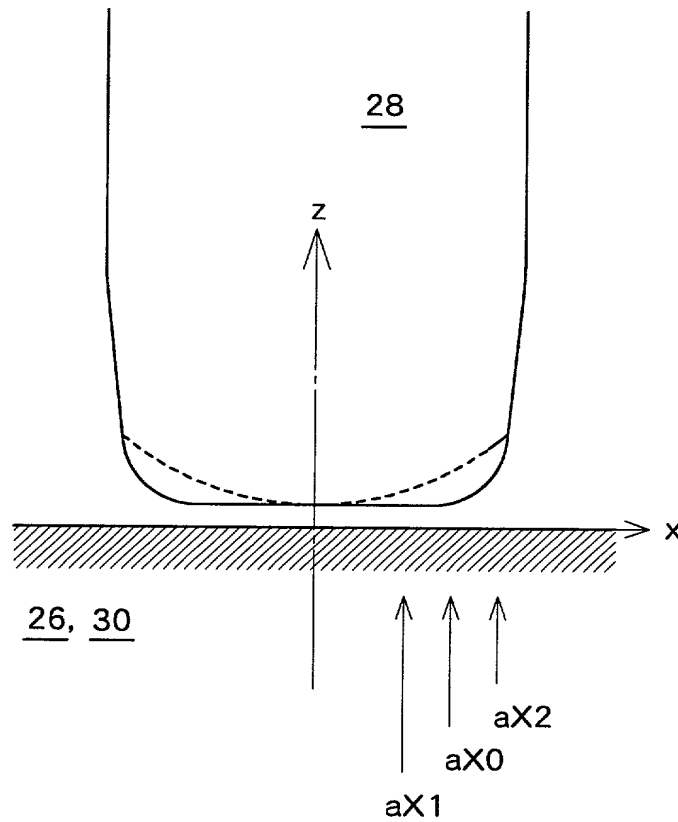


Fig.11

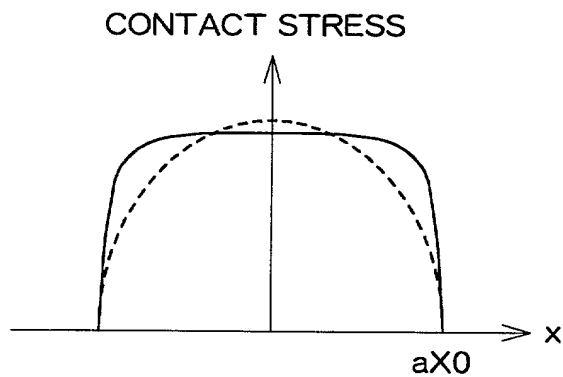


Fig.12

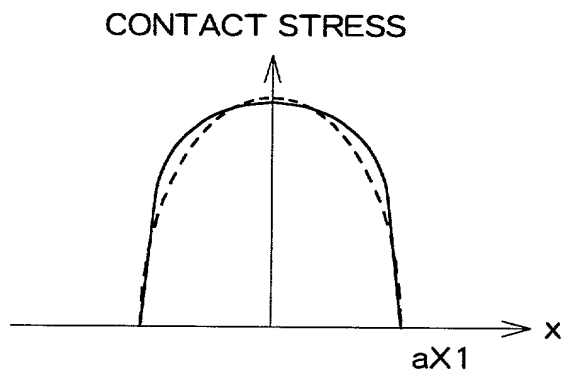


Fig.13

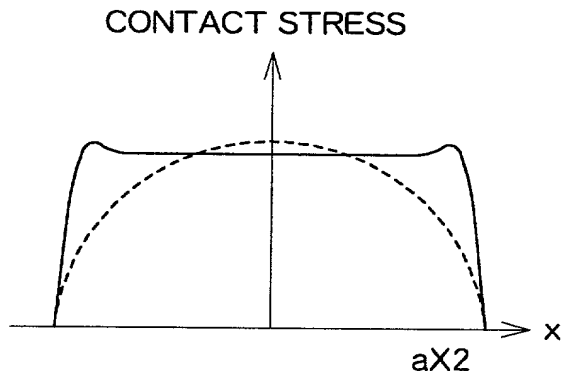
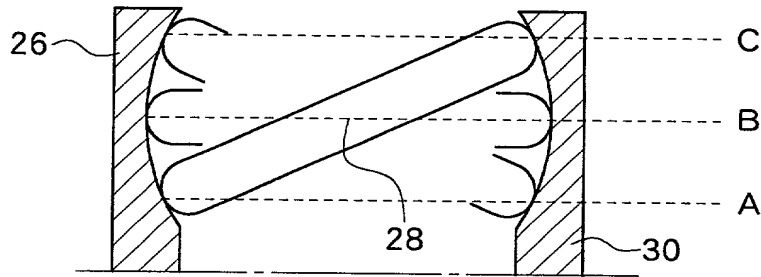


Fig.14

20250705/0001



SPEED CHANGING STATE	INPUT CONTACT	OUTPUT CONTACT
DECELERATION	A	C
CONSISTENT SPEED	B	B
ACCELERATION	C	A

Fig. 15

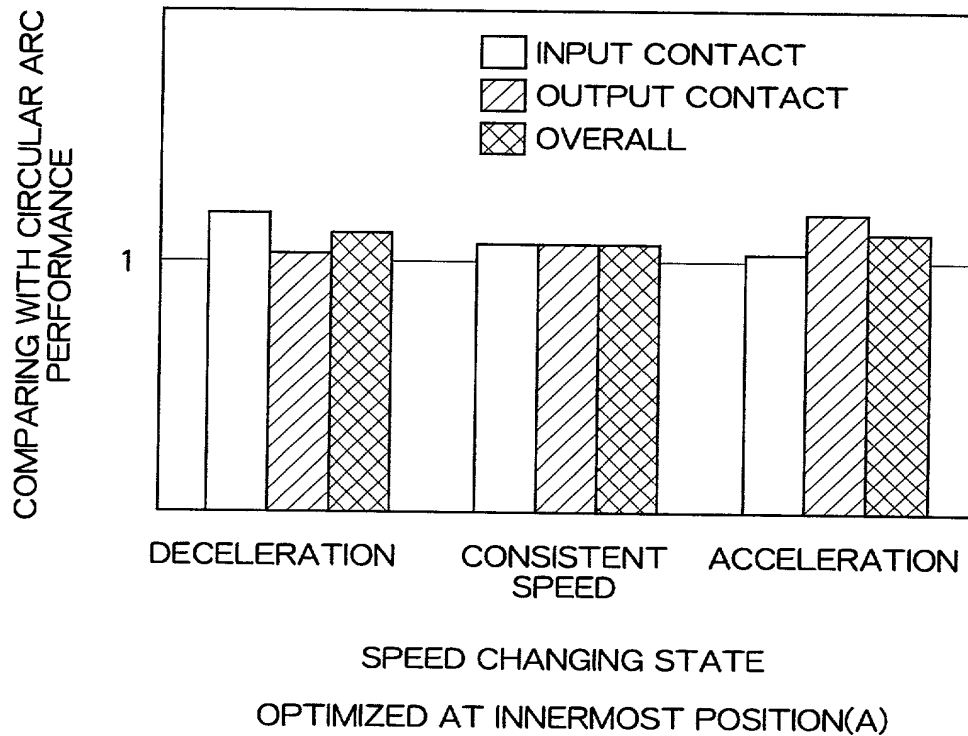


Fig. 16

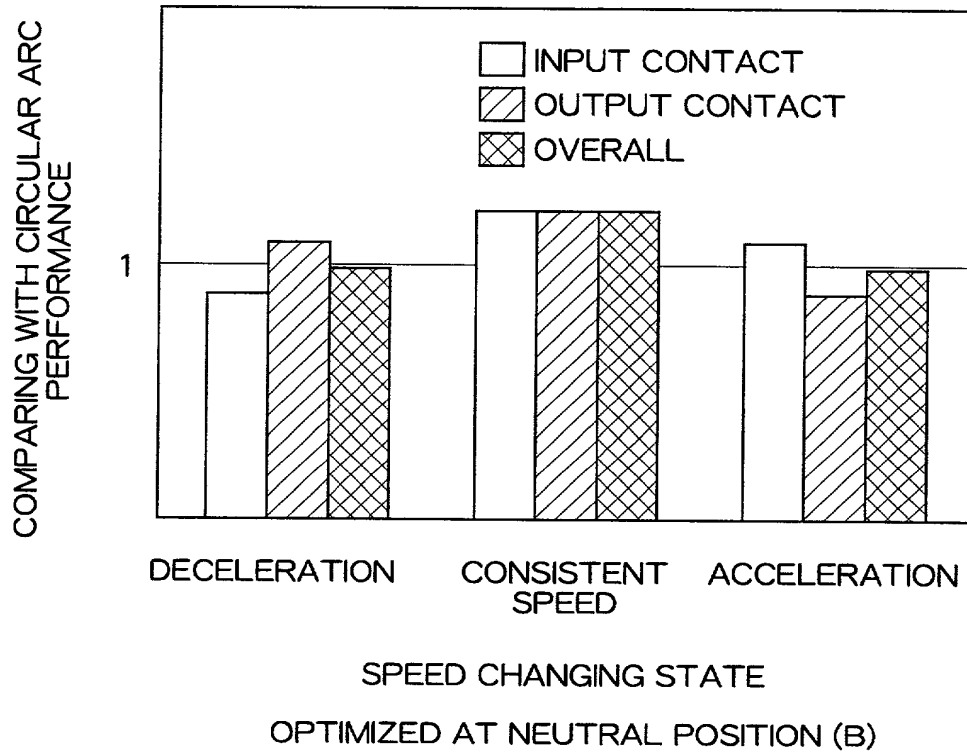


Fig.17

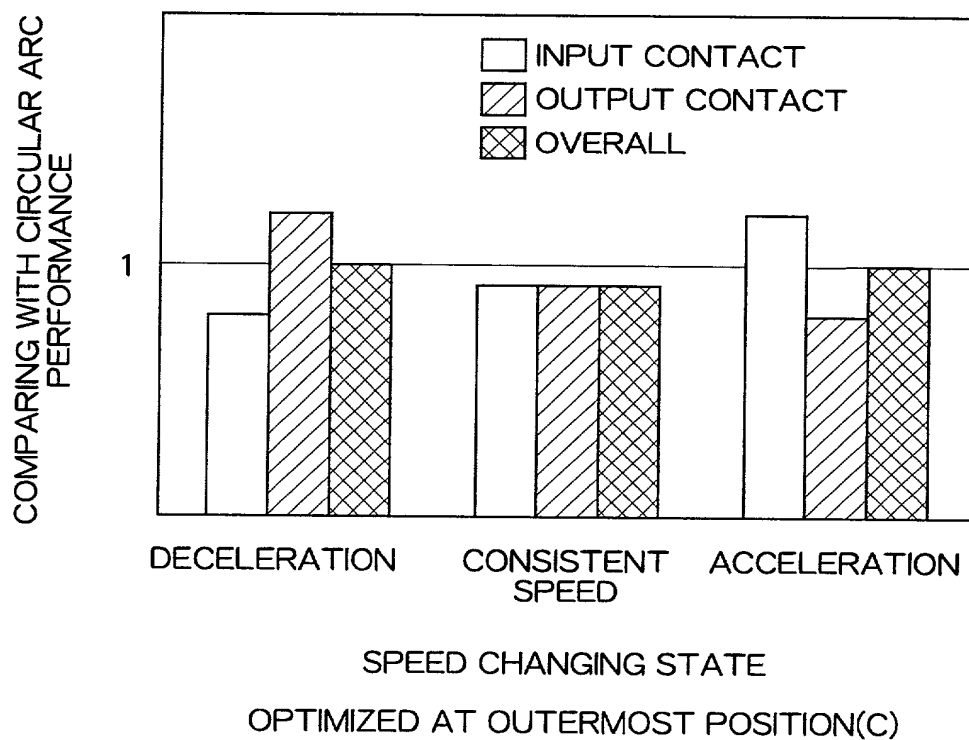


Fig.18

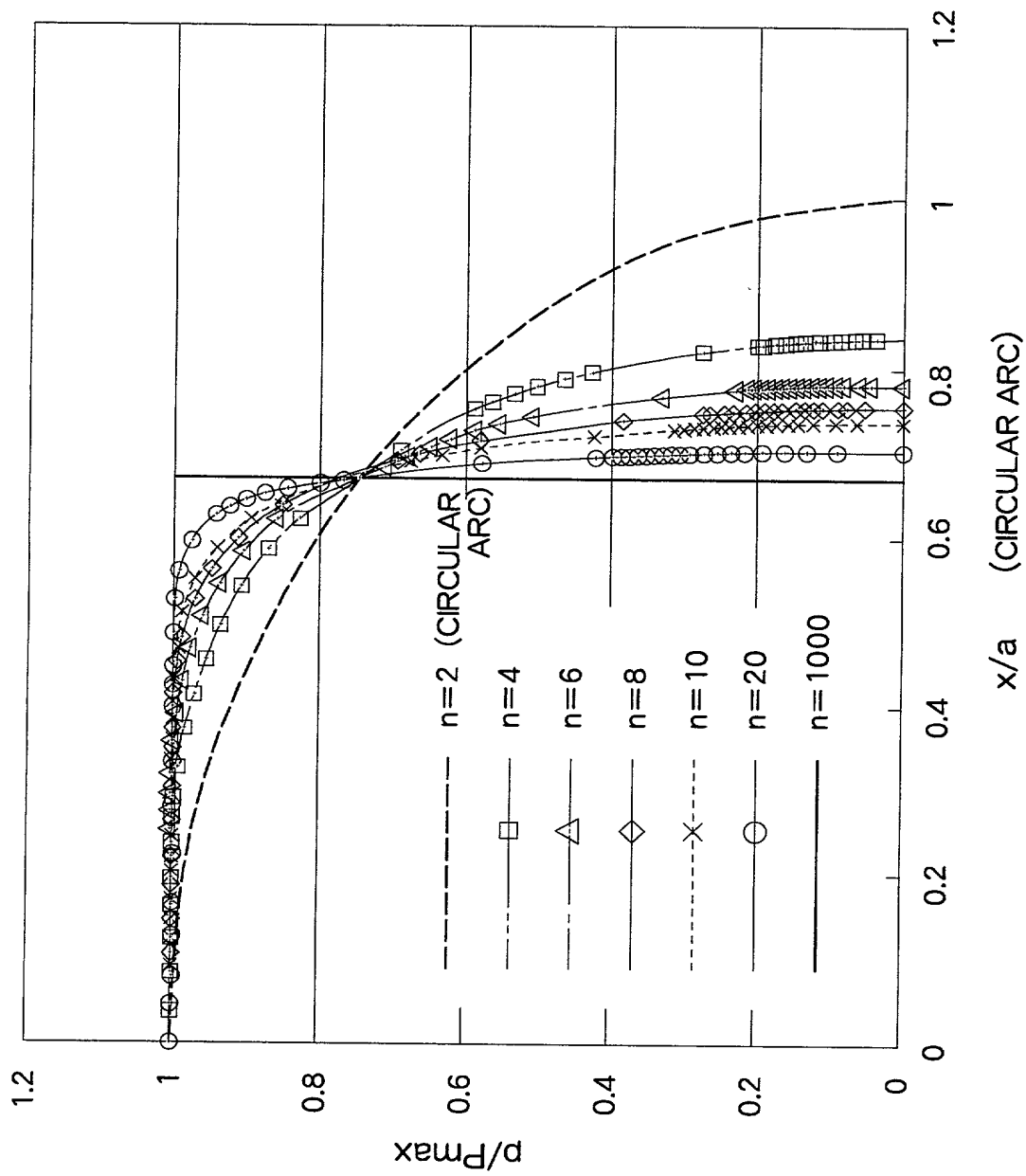


Fig.19

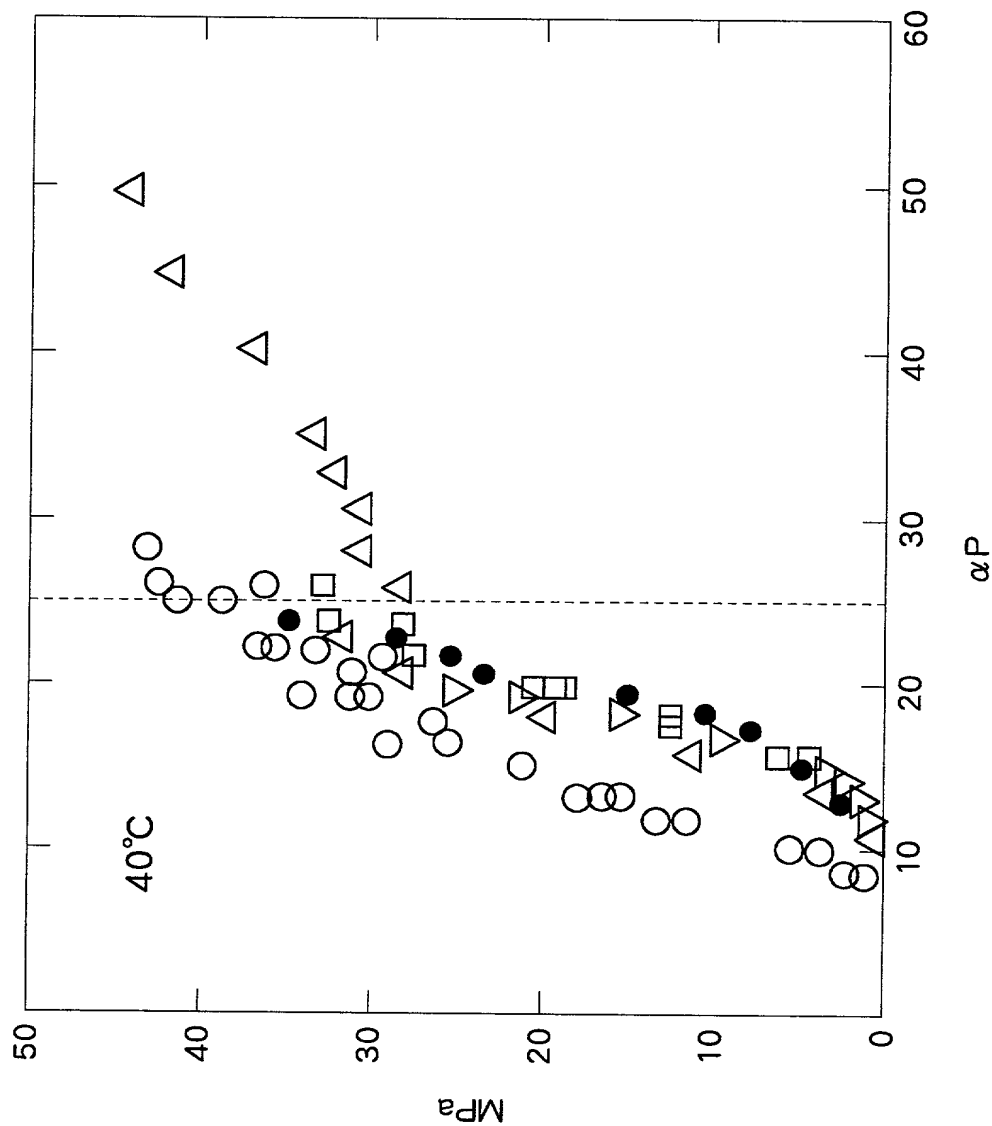


Fig.20

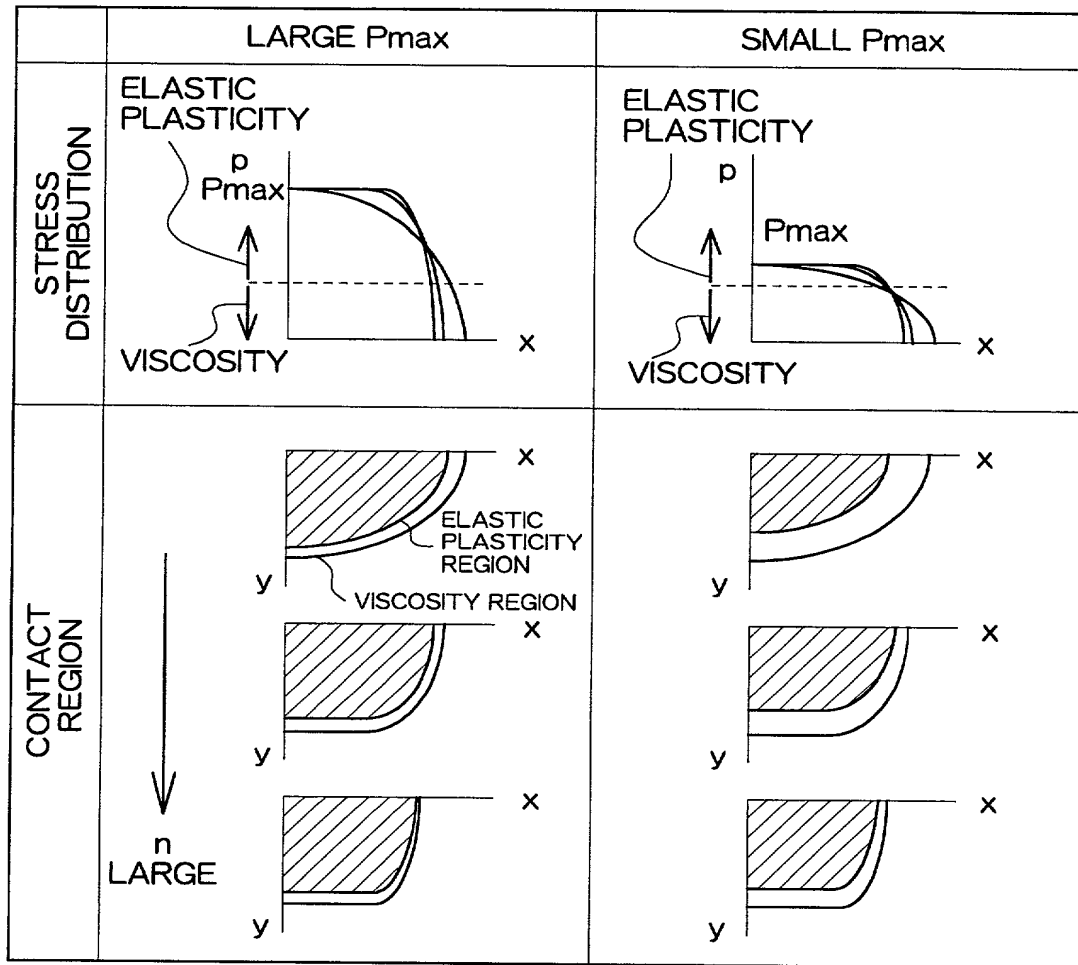


Fig.21

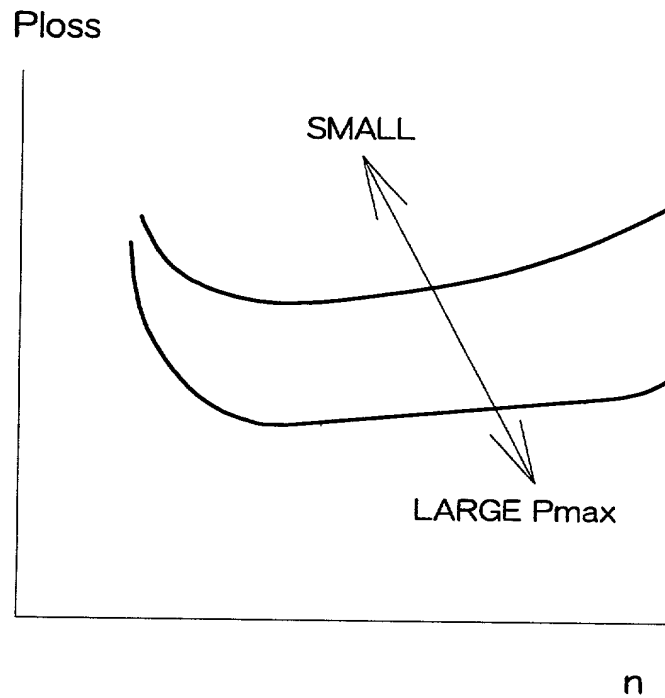


Fig.22

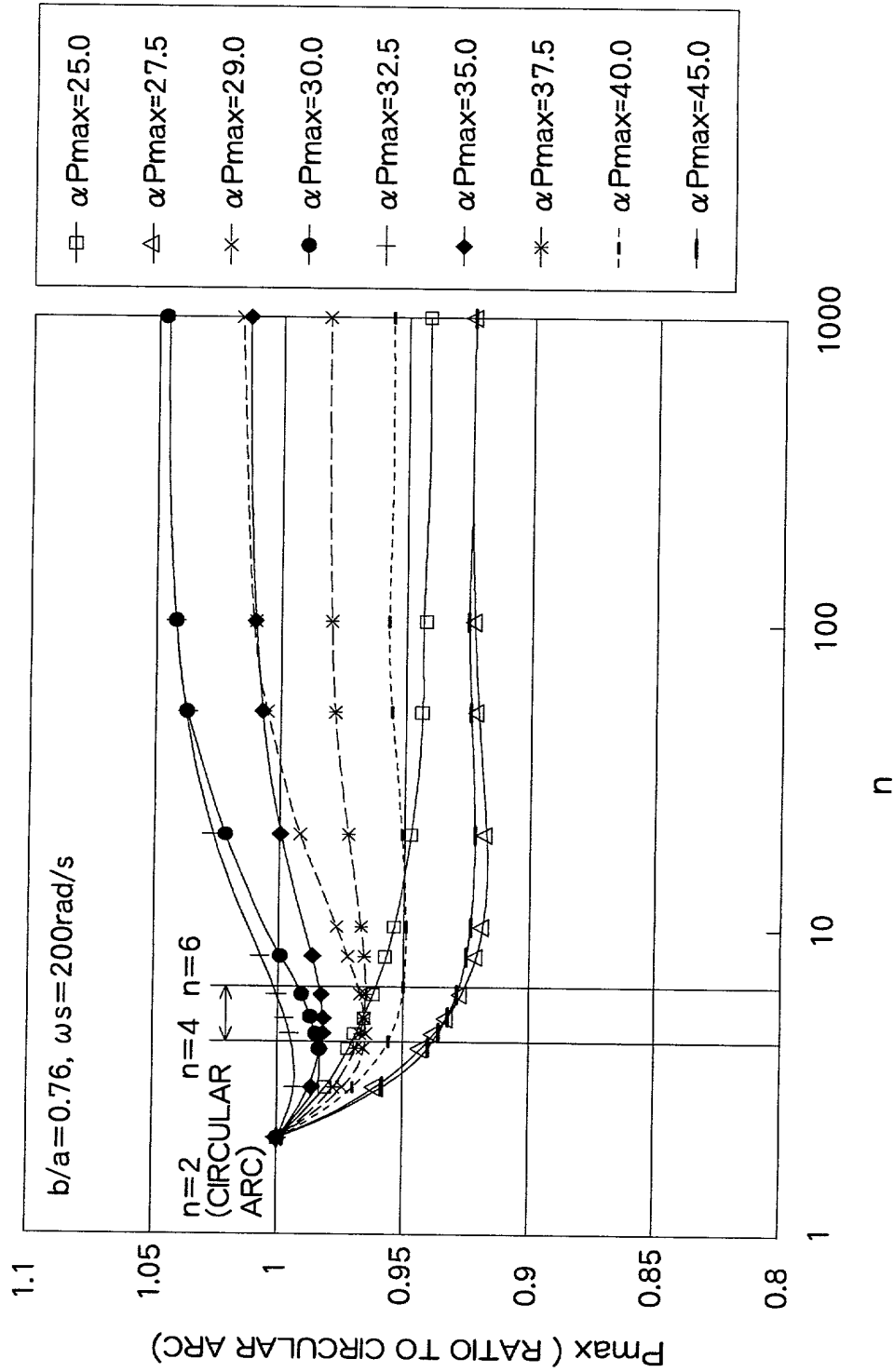


Fig.23

20250705 09:00

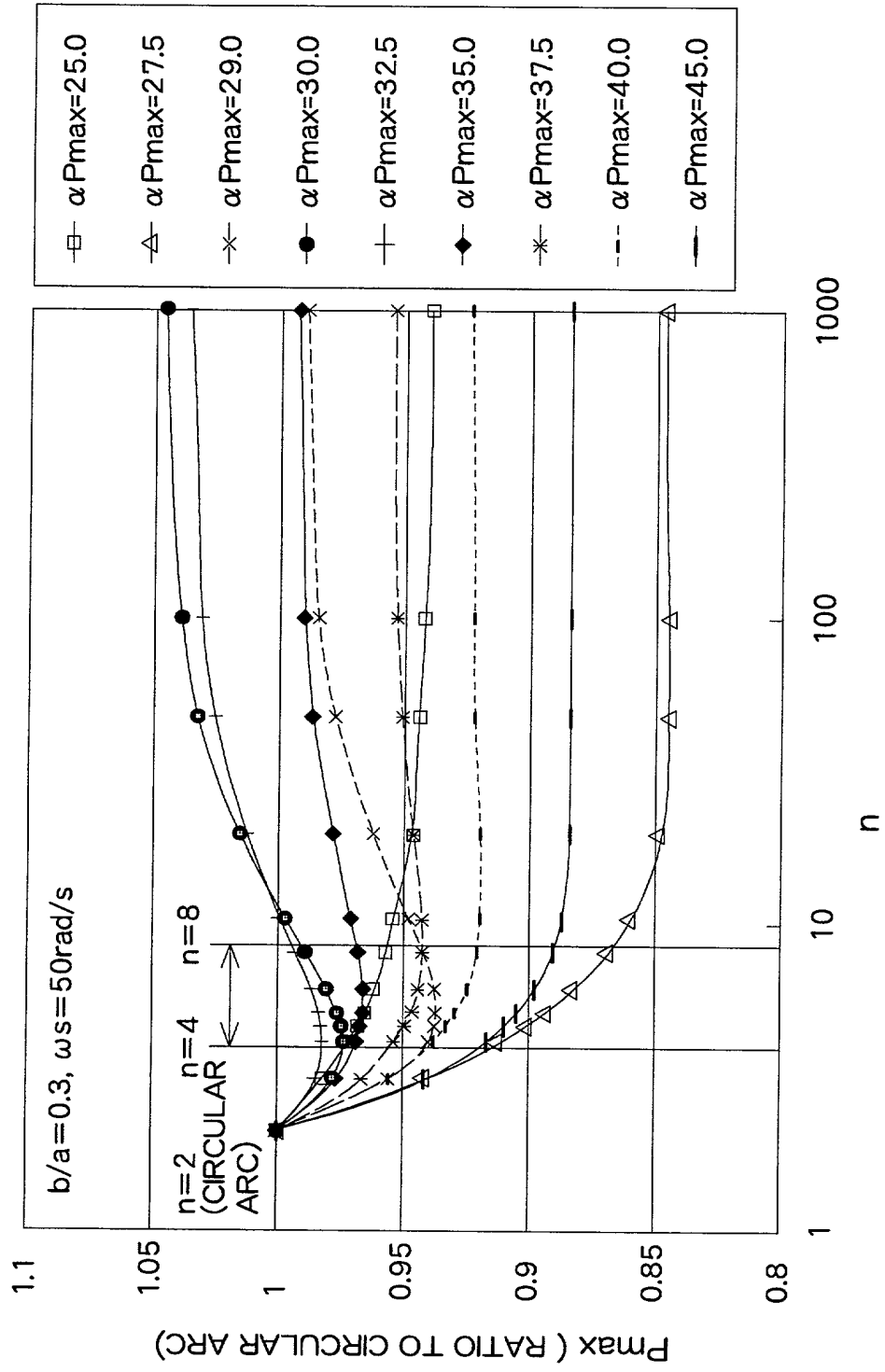


Fig.24

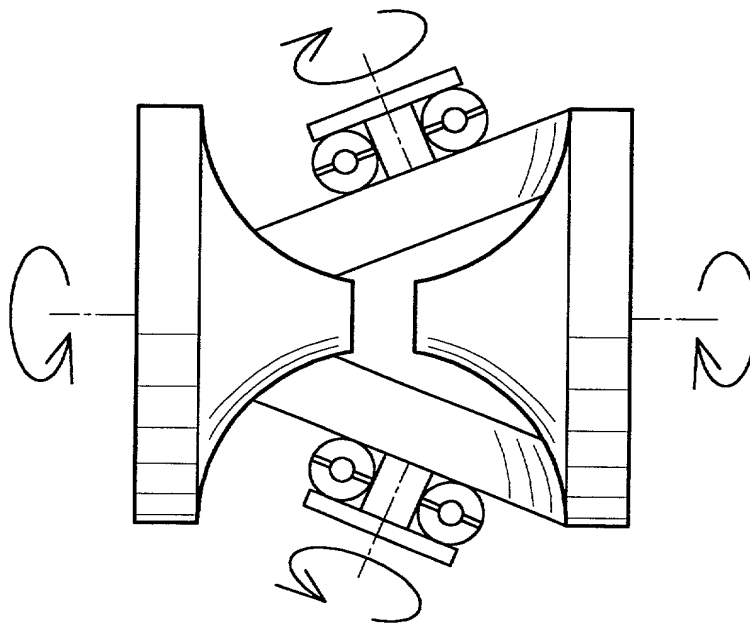


Fig.25

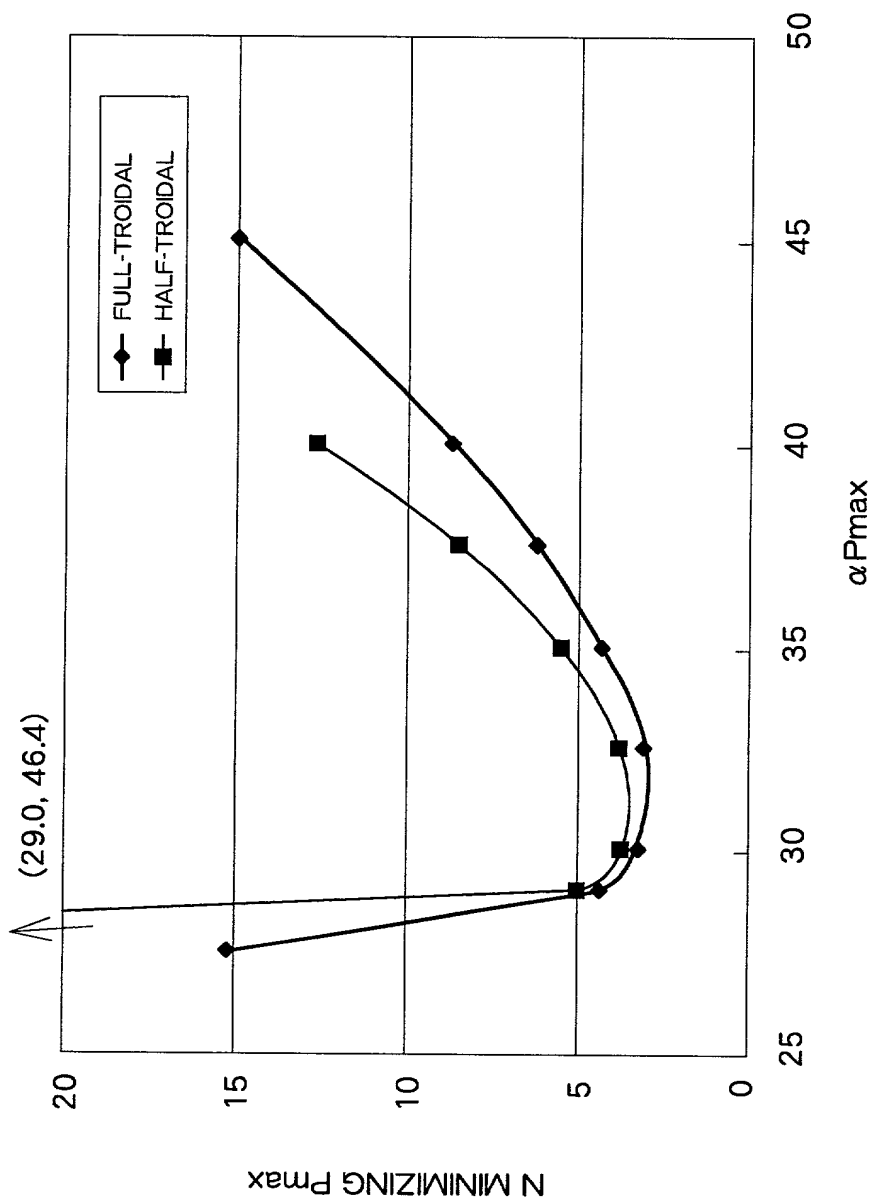


Fig.26

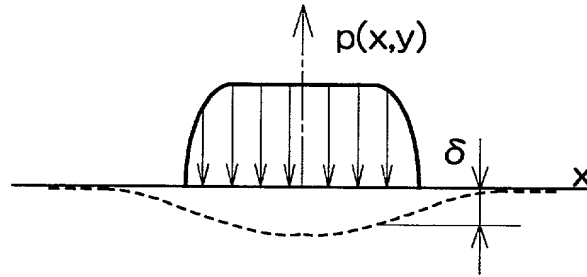


Fig.27A

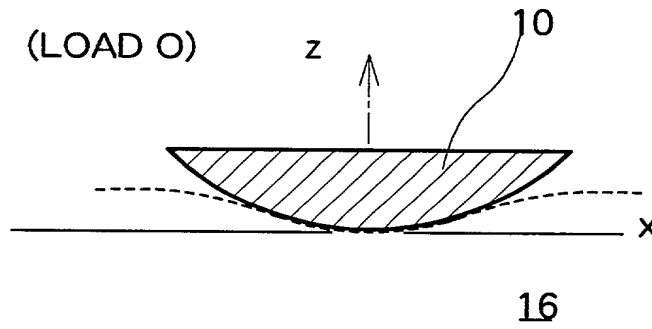


Fig.27B

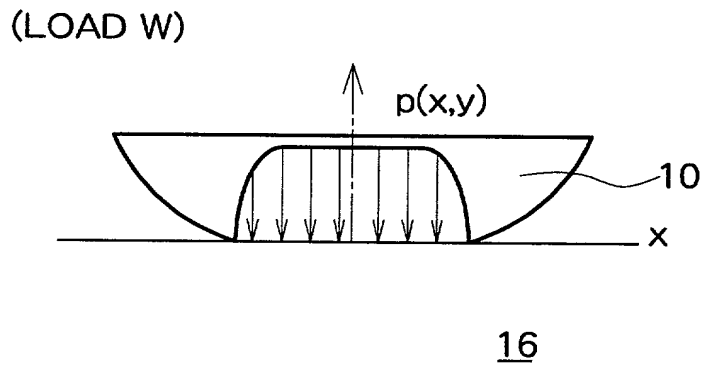


Fig.27C

10067403-020307

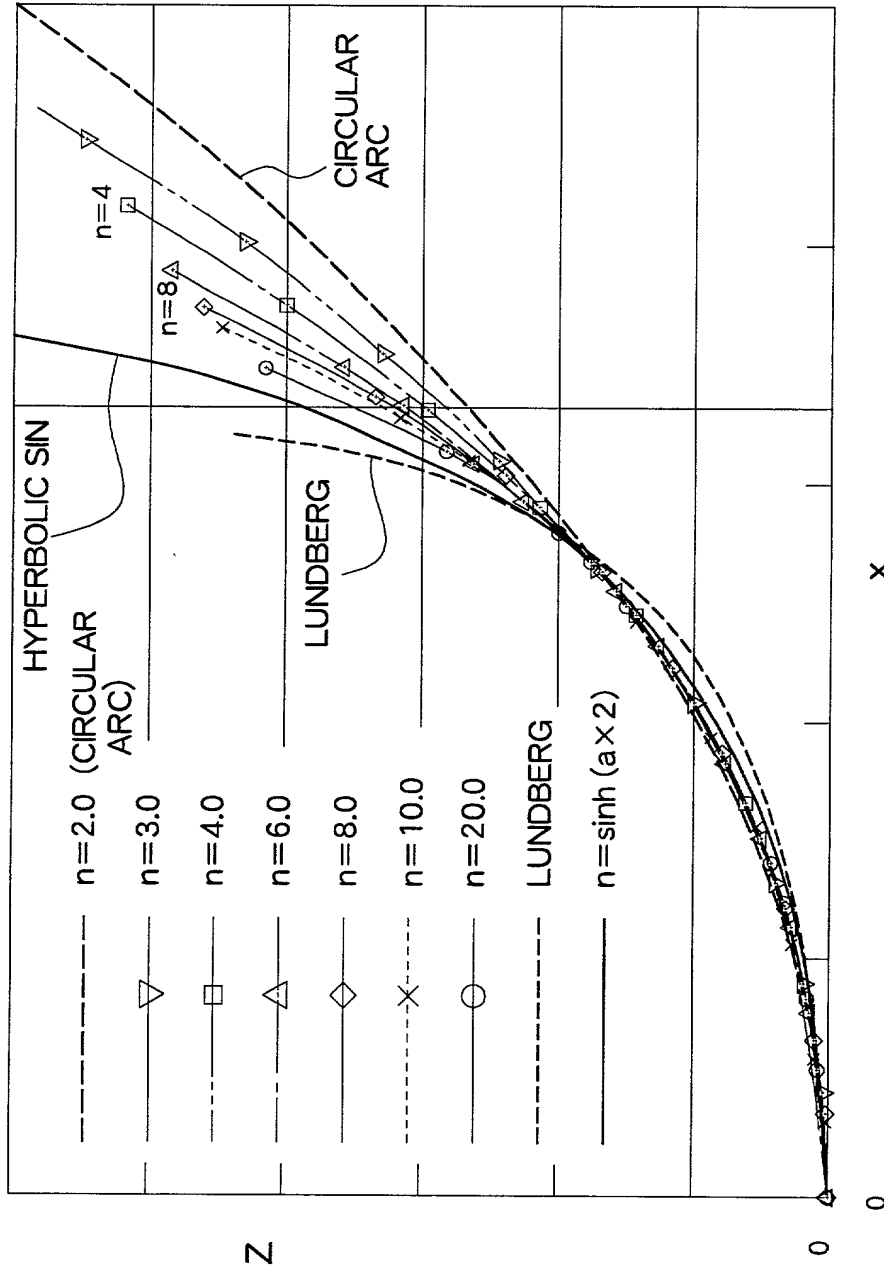


Fig.28